

Decomposition and cycles: isolating two complexity-generating mechanisms.

Andrea Aler Tubella

University of Bath

16th of November 2016

Decomposition

- ▶ In many systems, derivations can be arranged into consecutive subderivations made up of only certain rules: we call this transformation **decomposition**.
- ▶ Herbrand's Theorem is an example: bottom phase with contraction and quantifier rules and a top phase with propositional rules only.

Decomposition

- ▶ We can achieve a particular decomposition result for classical logic by doing local rewritings of proofs.
- ▶ We “move” atomic contractions downwards in a proof, and cocontractions upwards [3].
- ▶ The procedure can easily be visualised graphically.

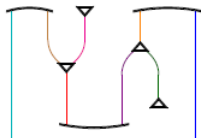
Decomposition

$$\begin{array}{ccc} \text{ai} \downarrow \frac{S\{t\}}{S[a, \bar{a}]} & & \text{ai} \uparrow \frac{S(a, \bar{a})}{S\{f\}} \\ & \text{s} \frac{S([R, U], T)}{S([R, T], U)} & \\ & \text{m} \frac{S([R, U], (T, V))}{S([R, T], [U, V])} & \\ \text{aw} \downarrow \frac{S\{f\}}{S\{a\}} & & \text{aw} \uparrow \frac{S\{a\}}{S\{t\}} \\ \text{ac} \downarrow \frac{S[a, a]}{S\{a\}} & & \text{ac} \uparrow \frac{S\{a\}}{S(a, a)} \end{array}$$

Figure: SKS [1]

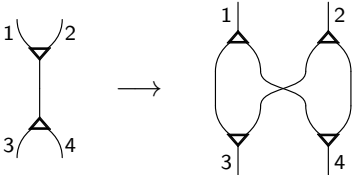
Atomic Flows [3]

$$\begin{aligned}
 & \frac{\frac{\frac{t}{a \vee \bar{a}}}{[a \vee t] \wedge [t \vee \bar{a}]}}{\frac{\frac{[a \vee t] \wedge \bar{a}}{a \wedge \bar{a}} \vee t}{f}} \\
 &= \frac{\frac{\frac{\frac{t}{\bar{a} \vee a} \vee \frac{f}{a}}{\bar{a} \vee \frac{a \vee a}{a}}}{\frac{[a \vee t] \wedge [t \vee \bar{a}]}{s^2}} \wedge \frac{\frac{t}{\bar{a}}}{\bar{a} \wedge \frac{\bar{a}}{t}} \vee a}{\frac{[a \wedge \bar{a}}{f} \vee t}} \\
 &= \frac{\frac{\frac{\frac{a}{a \wedge a} \vee \frac{b}{b \wedge b}}{[a \vee b] \wedge [a \vee b]}}{m} \wedge \frac{a}{a \wedge a}}{\frac{[a \vee t] \wedge [t \vee \bar{a}]}}{s}
 \end{aligned}$$



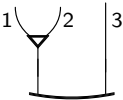
Decomposition

$$\begin{array}{c}
 \text{ac}\downarrow \frac{a^1 \vee a^2}{a} \\
 \text{ac}\uparrow \frac{a}{a^3 \wedge a^4}
 \end{array}
 \longrightarrow
 m \frac{
 \begin{array}{c}
 \boxed{\text{ac}\uparrow \frac{a^1}{a \wedge a}} \vee \boxed{\text{ac}\uparrow \frac{a^2}{a \wedge a}} \\
 \hline
 \boxed{\text{ac}\downarrow \frac{a \vee a}{a^3}} \wedge \boxed{\text{ac}\downarrow \frac{a \vee a}{a^4}}
 \end{array}
 }{
 }$$

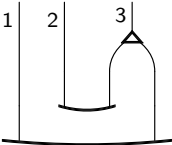


Decomposition

$$\begin{array}{c}
 \boxed{\text{ac}\downarrow \frac{a^1 \vee a^2}{a}} \wedge \bar{a}^3 \\
 \hline
 \text{ai}\uparrow \frac{\quad}{f}
 \end{array}
 \longrightarrow
 \begin{array}{c}
 (a^1 \vee a^2) \wedge \boxed{\text{ac}\uparrow \frac{\bar{a}^3}{\bar{a} \wedge \bar{a}}} \\
 \hline
 \text{s} \frac{\quad}{(a \wedge (\bar{a} \wedge \bar{a})) \vee a} \\
 \hline
 \text{s} \frac{\quad}{\boxed{\text{ai}\uparrow \frac{a \wedge \bar{a}}{f}} \vee \boxed{\text{ai}\uparrow \frac{a \wedge \bar{a}}{f}}} \\
 \hline
 = \frac{\quad}{f}
 \end{array}$$

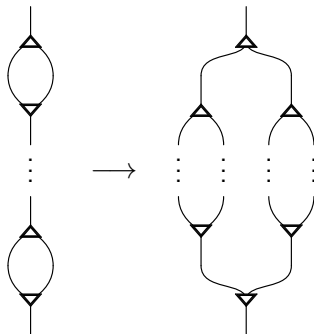


→



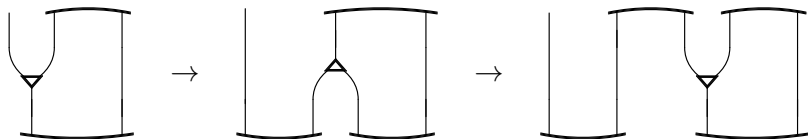
Complexity

- ▶ The decomposition procedure may increase the size of a proof exponentially.



Cycles

- ▶ When we apply the reductions to atomic contractions that belong to a cycle, the rewriting system is not terminating:



- ▶ Cycles come from the connexion of an introduction and a cut.

Why this decomposition?

- ▶ Not only decomposing proofs, but generally derivations.
- ▶ **Separation of compression mechanisms**
 - ▶ By separating into a phase with cuts and a phase with contractions, we divide cut-elimination into two separate procedures.
- ▶ Easily represented graphically.
- ▶ Seemingly more general than classical logic.
 - ▶ Analogous local reductions can be defined for LL [4].

Not all is settled

- ▶ Cycles.
 - ▶ Independence of decomposition from cut-elimination.
 - ▶ Proof compression? [2]
- ▶ Full decomposition into linear/non-linear phases.
- ▶ Generality.

A new methodology, that we call **subatomic**, allows us to tackle all three questions.

One shape to rule them all

- ▶ Many proof systems can be represented in such a way that every inference rule is an instance of a **single** linear inference rule scheme.

$$\frac{(A \alpha B) \beta (C \alpha' D)}{(A \beta C) \alpha (B \beta' D)}$$

But how?

- This shape arises very often when we have atomic introduction and contraction rules.

$$\begin{array}{ccc}
 \text{ai}\downarrow \frac{S\{t\}}{S[a, \bar{a}]} & & \text{ai}\uparrow \frac{S(a, \bar{a})}{S\{f\}} \\
 \\
 & \frac{S([R, U], T)}{S[(R, T), U]} & \\
 \text{m} & \frac{S[(R, U), (T, V)]}{S[(R, T), [U, V]]} & \\
 \\
 \text{aw}\downarrow \frac{S\{f\}}{S\{a\}} & & \text{aw}\uparrow \frac{S\{a\}}{S\{t\}} \\
 \\
 \text{ac}\downarrow \frac{S[a, a]}{S\{a\}} & & \text{ac}\uparrow \frac{S\{a\}}{S(a, a)}
 \end{array}$$

Figure: SKS [1]

$$\begin{array}{ccccccc}
 & \text{ai}\downarrow \frac{S\{1\}}{S[a, \bar{a}]} & & & \text{ai}\uparrow \frac{S(a, \bar{a})}{S\{1\}} & & \\
 & & & & & & \\
 & & & \frac{S([R, U], T)}{S[(R, T), U]} & & & \\
 & \text{d1} \frac{S\{[R, U], [T, V]\}}{S\{[R, T], [U, V]\}} & & & \text{d1} \frac{S\{[R, U], [T, V]\}}{S\{[R, T], [U, V]\}} & & \\
 & \text{p1} \frac{S\{[R, T]\}}{S\{[R, T]\}} & & & \text{p1} \frac{S\{[R, T]\}}{S\{[R, T]\}} & & \\
 \\
 \text{at}\downarrow \frac{S\{0\}}{S\{a\}} & & \text{ac}\downarrow \frac{S[a, a]}{S\{a\}} & & \text{ac}\uparrow \frac{S\{a\}}{S(a, a)} & & \text{at}\uparrow \frac{S\{a\}}{S\{T\}} \\
 \\
 \text{nm1} \frac{S\{0\}}{S\{0, 0\}} & & \text{m} \frac{S\{[R, U], [T, V]\}}{S\{[R, T], [U, V]\}} & & \text{nm1} \frac{S\{T, T\}}{S\{T\}} & & \\
 \\
 \text{nm1}\downarrow \frac{S\{0\}}{S\{0, 0\}} & & \text{m1}\downarrow \frac{S\{[R, U], [T, V]\}}{S\{[R, T], [U, V]\}} & & \text{m1}\downarrow \frac{S\{[R, U], [T, V]\}}{S\{[R, T], [U, V]\}} & & \text{nm1}\uparrow \frac{S\{T, T\}}{S\{T\}} \\
 \\
 \text{nm2}\downarrow \frac{S\{0\}}{S\{0, 0\}} & & \text{m2}\downarrow \frac{S\{[R, U], [T, V]\}}{S\{[R, T], [U, V]\}} & & \text{m2}\downarrow \frac{S\{[R, U], [T, V]\}}{S\{[R, T], [U, V]\}} & & \text{nm2}\uparrow \frac{S\{T, T\}}{S\{T\}} \\
 \\
 \text{nl1}\downarrow \frac{S\{0\}}{S\{0\}} & & \text{l1}\downarrow \frac{S\{[R, T]\}}{S\{[R, T]\}} & & \text{l1}\downarrow \frac{S\{[R, T]\}}{S\{[R, T]\}} & & \text{nl1}\uparrow \frac{S\{T\}}{S\{T\}} \\
 \\
 \text{nl2}\downarrow \frac{S\{0\}}{S\{0\}} & & \text{l2}\downarrow \frac{S\{[R, T]\}}{S\{[R, T]\}} & & \text{l2}\downarrow \frac{S\{[R, T]\}}{S\{[R, T]\}} & & \text{nl2}\uparrow \frac{S\{T\}}{S\{T\}} \\
 \\
 \text{nz}\downarrow \frac{S\{1\}}{S\{0\}} & & \text{z1}\downarrow \frac{S\{[R, T]\}}{S\{[R, T]\}} & & \text{z1}\downarrow \frac{S\{[R, T]\}}{S\{[R, T]\}} & & \text{nz}\uparrow \frac{S\{T\}}{S\{1\}}
 \end{array}$$

Figure: SLLS [4]

But how?

- ▶ How do the atomic rules fit the scheme?

We can consider atoms as superpositions of truth values:

$$\begin{array}{ll} f \mathbf{a} t \mapsto a & t \mathbf{a} f \mapsto \bar{a} \\ t \mathbf{a} t \mapsto t & f \mathbf{a} f \mapsto f \end{array}$$

- ▶ How does that change the rules?

Contraction:

$$\frac{(A \mathbf{a} B) \vee (C \mathbf{a} D)}{(A \vee C) \mathbf{a} (B \vee D)}$$

But how?

- ▶ How do the atomic rules fit the scheme?

We can consider atoms as superpositions of truth values:

$$\begin{array}{l} f \text{ } a \text{ } t \mapsto a \quad t \text{ } a \text{ } f \mapsto \bar{a} \\ t \text{ } a \text{ } t \mapsto t \quad f \text{ } a \text{ } f \mapsto f \end{array}$$

- ▶ How does that change the rules?

Contraction:

$$\frac{(f \text{ } a \text{ } t) \vee (f \text{ } a \text{ } t)}{(f \vee f) \text{ } a \text{ } (t \vee t)} \mapsto \frac{a \vee a}{a}$$

But how?

- ▶ How do the atomic rules fit the scheme?

We can consider atoms as superpositions of truth values:

$$\begin{array}{l} f \mathbf{a} t \mapsto a \quad t \mathbf{a} f \mapsto \bar{a} \\ t \mathbf{a} t \mapsto t \quad f \mathbf{a} f \mapsto f \end{array}$$

- ▶ How does that change the rules?

Contraction:

$$\frac{(t \mathbf{a} f) \vee (t \mathbf{a} f)}{(t \vee t) \mathbf{a} (f \vee f)} \mapsto \frac{\bar{a} \vee \bar{a}}{\bar{a}}$$

But how?

Two more examples, identity and cut:

$$\frac{(f \vee t) a (t \vee f)}{(f a t) \vee (t a f)} \mapsto \frac{t}{a \vee \bar{a}} \quad \text{and} \quad \frac{(f a t) \wedge (t a f)}{(f \wedge t) a (t \wedge f)} \mapsto \frac{a \wedge \bar{a}}{f} .$$

They are generated by the linear schemes:

$$\frac{(A \vee C) a (B \vee D)}{(A a B) \vee (C a D)} \quad \text{and} \quad \frac{(A a C) \wedge (B a D)}{(A \wedge B) a (C \wedge D)}$$

- Surprisingly, we are able to reduce disparate rules such as contraction, cut and identity into a unique rule scheme.

But how?

- ▶ Can we make proof systems for that?
 - ▶ **Not** in Gentzen formalisms.
 - ▶ **Yes** in Deep Inference.

- ▶ Deep Inference is necessary for complete proof systems with **self-dual non-commutative** connectives [5].

But how?

$$\begin{array}{ccc} \text{ai}\downarrow \frac{S\{t\}}{S[a, \bar{a}]} & & \text{ai}\uparrow \frac{S(a, \bar{a})}{S\{f\}} \\ & & \\ & \text{s} \frac{S([R, U], T)}{S([R, T], U)} & \\ & \text{m} \frac{S([R, U], (T, V))}{S([R, T], [U, V])} & \\ \text{aw}\downarrow \frac{S\{f\}}{S\{a\}} & & \text{aw}\uparrow \frac{S\{a\}}{S\{t\}} \\ \text{ac}\downarrow \frac{S[a, a]}{S\{a\}} & & \text{ac}\uparrow \frac{S\{a\}}{S(a, a)} \end{array}$$

Figure: SKS [1]

$$\begin{array}{ccc} \text{i}\downarrow \frac{[A \vee B] a [C \vee D]}{\langle A a C \rangle \vee \langle B a D \rangle} & & \text{i}\uparrow \frac{\langle A a B \rangle \wedge \langle C a D \rangle}{(A \wedge C) a (B \wedge D)} \\ & & \\ & \text{s} \frac{[A \vee B] \wedge [C \vee D]}{(A \wedge C) \vee [B \vee D]} & \\ & \text{m} \frac{(A \wedge B) \vee (C \wedge D)}{[A \vee C] \wedge [B \vee D]} & \\ \text{c}\downarrow \frac{\langle A a B \rangle \vee \langle C a D \rangle}{[A \vee C] a [B \vee D]} & & \text{c}\uparrow \frac{(A \wedge B) a (C \wedge D)}{\langle A a C \rangle \wedge \langle B a D \rangle} \end{array}$$

Figure: SAKS

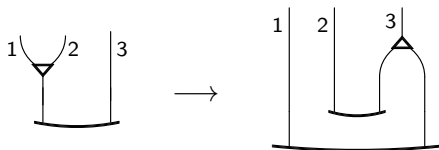
With subatomic logic

- ▶ We can generally study the interactions between rules.
- ▶ Some results:
 - ▶ We can represent a wide variety of systems with a single rule scheme, including CL and LL.
 - ▶ We provide a general cut-elimination theorem for a whole class of substructural logics.
 - ▶ In fact, we prove admissibility of a whole class of rules in a procedure of polynomial-time complexity.

We put it to use to generalise decomposition.

General decomposition

$$\begin{array}{c}
 \boxed{ac\downarrow \frac{a^1 \vee a^2}{a}} \wedge \bar{a}^3 \\
 \hline
 ai\uparrow \\
 f
 \end{array}
 \longrightarrow
 \begin{array}{c}
 (a^1 \vee a^2) \wedge \boxed{ac\uparrow \frac{\bar{a}^3}{\bar{a} \wedge \bar{a}}} \\
 \hline
 s \\
 (a \wedge (\bar{a} \wedge \bar{a})) \vee a \\
 \hline
 s \\
 \boxed{ai\uparrow \frac{a \wedge \bar{a}}{f}} \vee \boxed{ai\uparrow \frac{a \wedge \bar{a}}{f}} \\
 \hline
 = \\
 f
 \end{array}$$

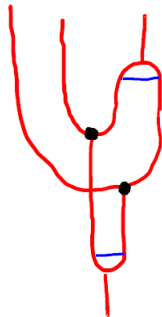
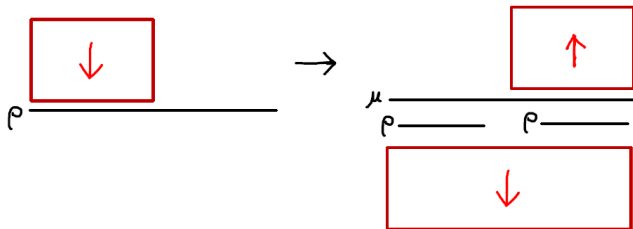


General decomposition

$$i\uparrow \frac{c\downarrow \frac{(f \ a \ t) \vee (f \ a \ t)}{f \ a \ t} \wedge t \ a \ f}{f} \longrightarrow$$

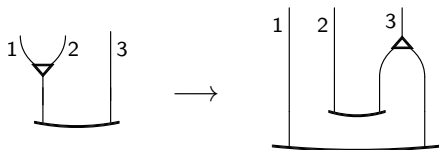
$$\begin{array}{c}
 ((f \ a \ t) \vee (f \ a \ t)) \wedge c\uparrow \frac{t \ a \ f}{(t \ a \ f) \wedge (t \ a \ f)} \\
 \hline
 s \frac{((f \ a \ t) \wedge (t \ a \ f) \wedge (t \ a \ f)) \vee (f \ a \ t)}{s} \\
 \hline
 s \frac{(f \ a \ t) \wedge (t \ a \ f) \quad (f \ a \ t) \wedge (t \ a \ f)}{i\uparrow \frac{(f \wedge t) \ a \ (t \wedge f) \quad \vee \quad i\uparrow \frac{(f \wedge t) \ a \ (t \wedge f)}{(f \wedge t) \ a \ (t \wedge f)}}{c\downarrow \frac{((f \wedge t) \vee (f \wedge t)) \ a \ ((t \wedge f) \vee (t \wedge f))}}
 \end{array}$$

General decomposition



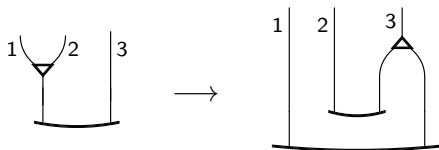
General decomposition

$$\begin{array}{c}
 \boxed{ac\downarrow \frac{a^1 \vee a^2}{a}} \wedge \bar{a}^3 \\
 \hline
 ai\uparrow \\
 f
 \end{array}
 \longrightarrow
 \begin{array}{c}
 (a^1 \vee a^2) \wedge \boxed{ac\uparrow \frac{\bar{a}^3}{\bar{a} \wedge \bar{a}}} \\
 \hline
 s \\
 (a \wedge (\bar{a} \wedge \bar{a})) \vee a \\
 \hline
 s \\
 \boxed{ai\uparrow \frac{a \wedge \bar{a}}{f}} \vee \boxed{ai\uparrow \frac{a \wedge \bar{a}}{f}} \\
 \hline
 = \\
 f
 \end{array}$$



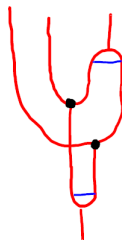
General decomposition

$$\begin{array}{c}
 \boxed{ac\downarrow \frac{a^1 \vee a^2}{a}} \wedge \bar{a}^3 \\
 \hline
 ai\uparrow \\
 f
 \end{array}
 \longrightarrow
 \begin{array}{c}
 (a^1 \vee a^2) \wedge \boxed{ac\uparrow \frac{\bar{a}^3}{\bar{a} \wedge \bar{a}}} \\
 \hline
 s \\
 (a \wedge (\bar{a} \wedge \bar{a})) \vee a \\
 \hline
 s \\
 \boxed{\frac{ai\uparrow \frac{a \wedge \bar{a}}{f}}{f}} \vee \boxed{\frac{ai\uparrow \frac{a \wedge \bar{a}}{f}}{f}} \\
 \hline
 = \\
 f
 \end{array}$$



General decomposition

$$\begin{array}{c}
 \boxed{ac\downarrow \frac{a^1 \vee a^2}{a}} \wedge \bar{a}^3 \\
 \hline
 ai\uparrow \\
 f
 \end{array}
 \rightarrow
 \begin{array}{c}
 (a^1 \vee a^2) \wedge \boxed{ac\uparrow \frac{\bar{a}^3}{\bar{a} \wedge \bar{a}}} \\
 \hline
 s \\
 (a \wedge (\bar{a} \wedge \bar{a})) \vee a \\
 \hline
 s \\
 \boxed{\begin{array}{c} a \wedge \bar{a} \\ ai\uparrow \frac{\quad}{f} \end{array}} \vee \boxed{\begin{array}{c} a \wedge \bar{a} \\ ai\uparrow \frac{\quad}{f} \end{array}} \\
 \hline
 = \\
 f
 \end{array}$$



General decomposition

- ▶ This reduction shape can be observed frequently.
- ▶ It can be generalised to provide reductions for all contractive rules.
- ▶ We can characterise those systems for which these reduction rules are sound.

General decomposition

Theorem (Pending approval)

We can decompose derivations into an introductory phase followed by a contractive phase.

(In a certain class of systems including CL and MALL)

General decomposition

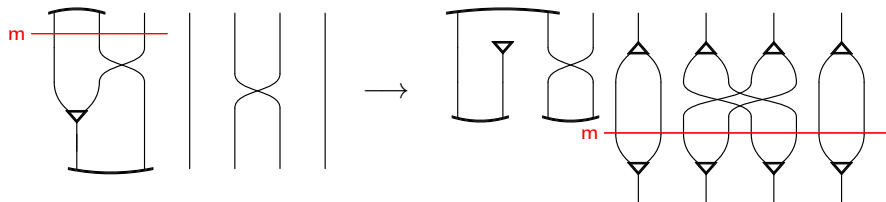
$$\begin{array}{c}
 \begin{array}{|c|} \hline (A \wedge B) \vee (C \wedge D) \\ \hline \end{array} \\
 \begin{array}{|c|} \hline m \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline A \vee C & B \vee D \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline \|c & \|c \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline M & N \\ \hline \end{array} \\
 \wedge (E \vee F) \\
 \hline s \\
 (M \wedge E) \vee (N \wedge F)
 \end{array}
 \rightarrow
 \begin{array}{c}
 \begin{array}{|c|} \hline E \vee F \\ \hline \end{array} \\
 \begin{array}{|c|} \hline \|c \\ \hline \end{array} \\
 \begin{array}{|c|} \hline (E \vee F) \wedge (E \vee F) \\ \hline \end{array} \\
 \wedge ((A \wedge B) \vee (C \wedge D)) \\
 \hline s \\
 \begin{array}{|c|c|} \hline (A \wedge B) \wedge (E \vee F) & (C \wedge D) \wedge (E \vee F) \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline s & s \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline (A \wedge E) \vee (B \wedge F) & (C \wedge E) \vee (D \wedge F) \\ \hline \end{array} \\
 \vee \\
 \hline = \\
 \begin{array}{|c|c|} \hline (A \wedge E) \vee (C \wedge E) & (B \wedge F) \vee (D \wedge F) \\ \hline \end{array} \\
 \begin{array}{|c|} \hline m \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline A \vee C & E \vee E \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline \|c & \|c \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline M & E \\ \hline \end{array} \\
 \wedge \\
 \begin{array}{|c|c|} \hline B \vee D & F \vee F \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline \|c & \|c \\ \hline \end{array} \\
 \begin{array}{|c|c|} \hline N & F \\ \hline \end{array} \\
 \vee \\
 \hline
 \end{array}$$

Cycle elimination

Theorem

Given a derivation with a cycle, there exists a cycle-free derivation with the same premiss and conclusion.

(In CL and MALL.)



Conclusions

- ▶ We observe a striking phenomenon: only one rule shape is enough to describe many different systems.
- ▶ We are able to observe that complexity comes from decomposition rather than from splitting.
- ▶ We wonder what role cycles play as a compression mechanism.
- ▶ We would like to use it as a stepping stone towards a geometrical formalism.

References

- [1] K. Brünnler and A. F. Tiu.
A local system for classical logic.
In R. Nieuwenhuis and A. Voronkov, editors, *Logic for Programming, Artificial Intelligence, and Reasoning (LPAR)*, volume 2250 of *Lecture Notes in Computer Science*, pages 347–361. Springer-Verlag, 2001.
- [2] A. Carbone.
The cost of a cycle is a square.
The Journal of Symbolic Logic, 67(1):35–61, March 2002.
- [3] T. Gundersen.
A General View of Normalisation Through Atomic Flows.
PhD thesis, University of Bath, 2009.
- [4] L. Straßburger.
Linear Logic and Noncommutativity in the Calculus of Structures.
PhD thesis, Technische Universität Dresden, 2003.
- [5] A. Tiu.
A system of interaction and structure II: The need for deep inference.
Logical Methods in Computer Science, 2(2):4:1–24, 2006.